

Contents

Symbols and Acronyms	vii
Abstract	ix
Deutsche Kurzfassung	xi
1. Introduction	1
1.1. Motivation	1
1.2. Contribution and Outline of this Thesis	2
2. Sparsity Promoting Optimization	5
2.1. Sparsity Measures and Their Use in Optimization	5
2.2. Block Sparsity and Pattern Operator	9
3. Decentralized Control of Interconnected Systems	11
3.1. Overview	11
3.2. Interconnected Systems	13
3.3. State Feedback	14
3.3.1. Centralized Controllers	14
3.3.2. Decentralized Controllers	14
3.3.3. Performance Degradation due to Decentralized Controller .	16
3.3.4. Decentralized Control Problem	17
3.3.5. Convex Relaxation	18
Convex Relaxation of the ℓ_0 -constraint	18
Reformulation of the \mathcal{H}_∞ -performance Constraint	18
3.3.6. Relaxed Decentralized Controller Design	21
3.4. Static Output Feedback	23
3.4.1. Decentralized Control Problem	24
3.4.2. Convex Relaxation	25
3.4.3. Initial Value Optimization	28
3.5. Dynamic Output Feedback	29
3.5.1. Decentralized Control Problem	32
3.5.2. Convex Relaxation	33
3.5.3. Alternative Dynamic Output Feedback Controllers	33
3.6. Application Example: Wide Area Control of Power Systems	35
3.6.1. Nominal Controller Design	37
3.6.2. Robustness Analysis of the Nominal Controller	40
3.7. Summary	45

4. Sparse Topology Design for Dynamical Networks	47
4.1. Overview	47
4.2. Review of Models for Consensus and Relative Sensing Networks	50
4.2.1. Consensus Networks	50
4.2.2. Relative Sensing Networks	52
4.3. Synthesis of Consensus Networks	54
4.3.1. Problem Formulation	54
4.3.2. Optimization Algorithm	55
4.3.3. Numerical Example	58
4.4. Synthesis of Sparse Relative Sensing Networks	63
4.4.1. Nominal Design	63
Problem Formulation	64
Optimization Algorithm	65
Example	66
4.4.2. Robust Design	70
Problem Formulation	71
Optimization Algorithm	73
Example	73
4.5. Summary	76
5. ℓ_0-Gain and ℓ_1-Optimal Control	79
5.1. Overview	79
5.2. The ℓ_0 -System Gain	80
5.3. The ℓ_0 -Optimal Control Problem	81
5.4. Lagrangian Relaxation of the ℓ_0 -Optimal Control Problem	83
5.5. The ℓ_1 -Optimal Control Problem	88
5.6. Summary	89
6. Conclusion	91
6.1. Summary	91
6.2. Outlook	92
A. Auxiliary Results	95
A.1. Matrix Inequalities	95
A.2. Loop Shifting	96
A.3. Linear Fractional Transformations	96
A.4. Youla Parametrization	97
B. Signal and Operator Norms	99
B.1. Vector and Signal Norms	99
B.2. Operator Norms	99
C. Graph Theory	101
C.1. Graphs, Spanning Trees, and Cycles	101
C.2. The Edge Laplacian	103
Bibliography	104